

## Algorithm-Hardware Co-design for Deformable Convolution

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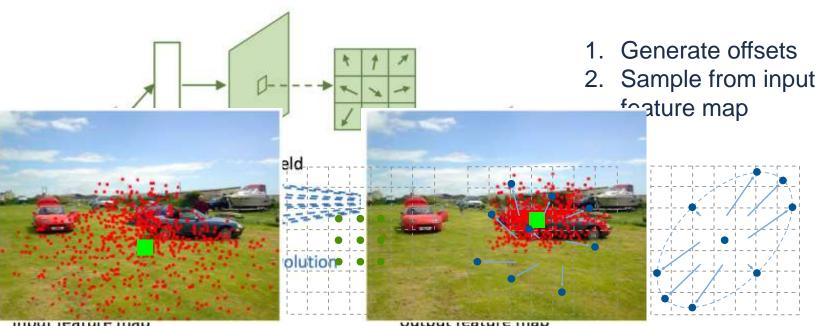
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### Motivation

- **Deformable Convolution** is an input-adaptive dynamic operation that samples inputs from variable spatial locations
- Its sampling locations vary with:
  - Different in
  - Different ou
- It captures the
  - Scales
  - Aspect Rat
  - Rotation Ar
- Challenges:
  - Increasec
  - Irregular |
    - Not frie

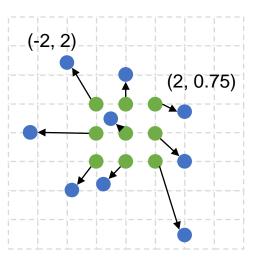


Sampling Locations (in red) for Different Output Dixesceptore melds



# Algorithm-Hardware Codesign

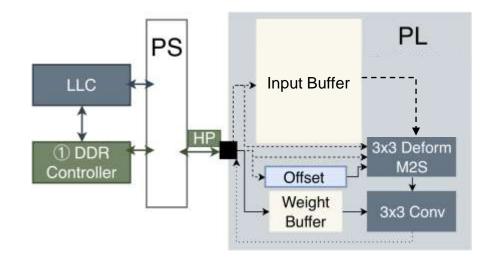
#### Algorithm Modification:



0. Original Deformable

Accuracy <sup>1</sup>(mIoU  $\uparrow$ ): **79.9** 

#### Hardware Optimization:

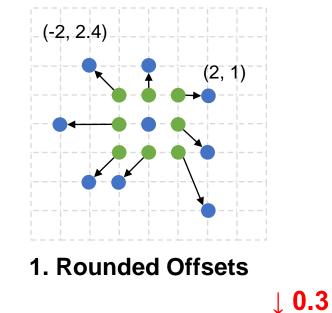


- Preloads weights to on-chip buffer
- Loads input and offsets directly from DRAM



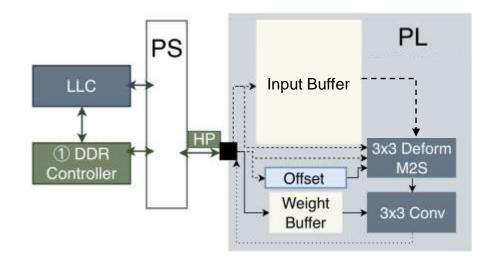
# Algorithm-Hardware Codesign

Algorithm Modification:



Accuracy <sup>1</sup>(mIoU ↑): **79.6** 

Hardware Optimization:



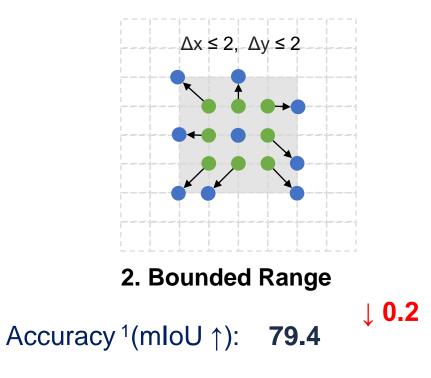
Reduces the computation for bilinear interpolation

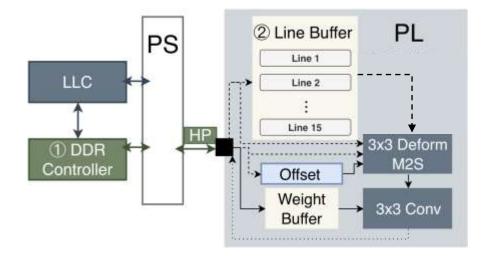


## Algorithm-Hardware Codesign

Algorithm Modification:

Hardware Optimization:





• Buffers inputs in the on-chip line buffer to allow spatial reuse



# **Resolitshm-Hardware Codesign**

### Hardware Performance

Hardware Optimization:

Operation	Original	Deformable	Bound	Square	Without LLC		With LLC	
			(buffered)	(multi-ported)	Latency (ms)	GOPs	Latency (ms)	GOPs
Full 3×3 Conv	$\checkmark$				43.1	112.0	41.6	116.2
		$\checkmark$			59.0	81.8	42.7	113.1
		$\checkmark$	$\checkmark$		43.4	111.5	41.8	115.5
		$\checkmark$	$\checkmark$	$\checkmark$	43.4	111.5	41.8	115.6
Depthwise 3×3 Conv	$\checkmark$				1.9	9.7	2.0	9.6
		$\checkmark$			20.5	0.9	17.8	1.1
		$\checkmark$	$\checkmark$		3.0	6.2	3.4	5.5
		$\checkmark$	$\checkmark$	✓	2.1	9.2	2.3	8.2

5-Oeptays Rectangulation warse co-design methodology for the deformable Convolution achieves and .36× and 9.76וspeaker is stand with the set of the deformable convolution on FPGA ShuffleNetV2 Deform Conv Depthwise 68.0 Email: Gijing huang Oberkeley.edu

