Energy-Aware Neural Architecture Optimization with Splitting Steepest Descent

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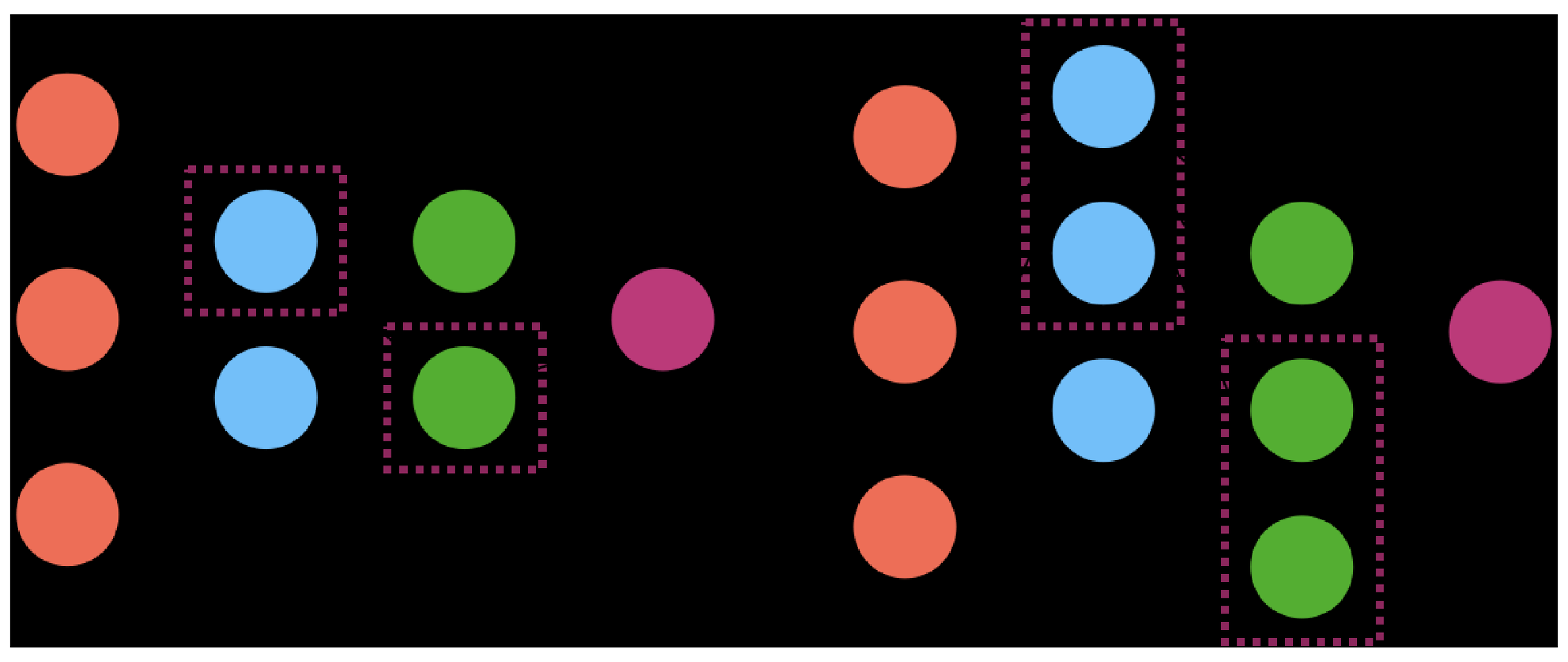
Neural architecture optimization

Splitting Yields Adaptive Net Structure Optimization

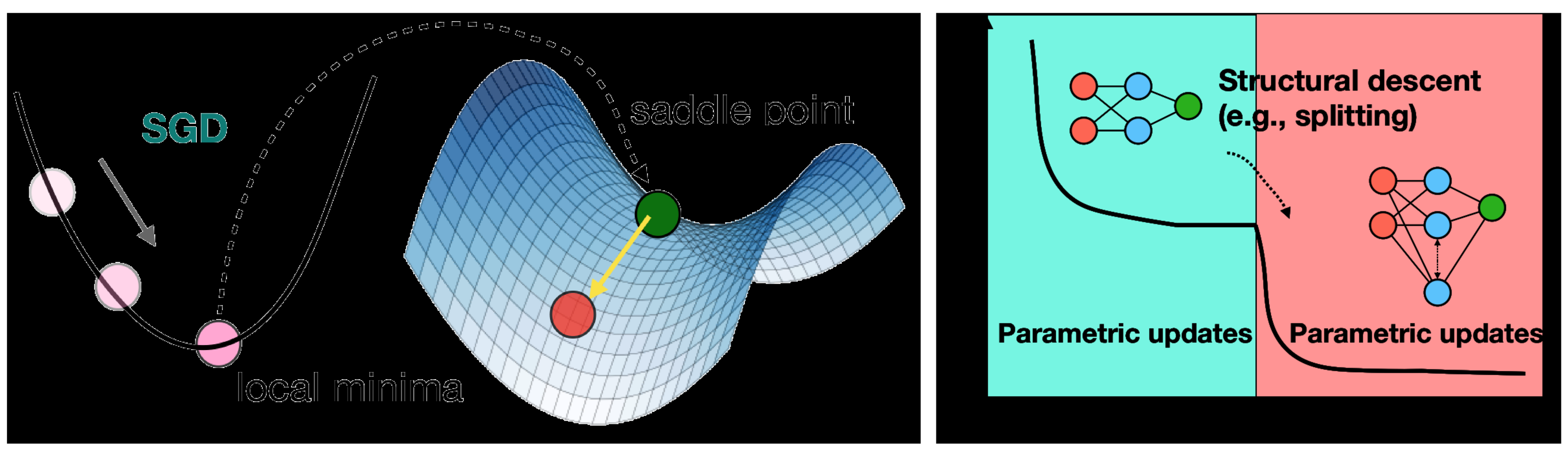
- Starting from a small net, gradually grow the net during training.
- Grow by "splitting" existing neurons into multiple off-springs.



Why, when and how?

- Why splitting? Does splitting decrease the loss? How much?
- When to split? What neurons should be split first?
- How to split a neuron optimally? How many copies to split into?

Why & when: escaping local minima



- **Optimization view**: the local optima in the low dimensional space can be turned into a saddle point in a higher dimensional of the augmented networks
- **Architecture view**: lower-dimensional space → smaller networks; higher-dimensional space → larger networks

How: splitting steepest descent

- Consider a single-neuron network

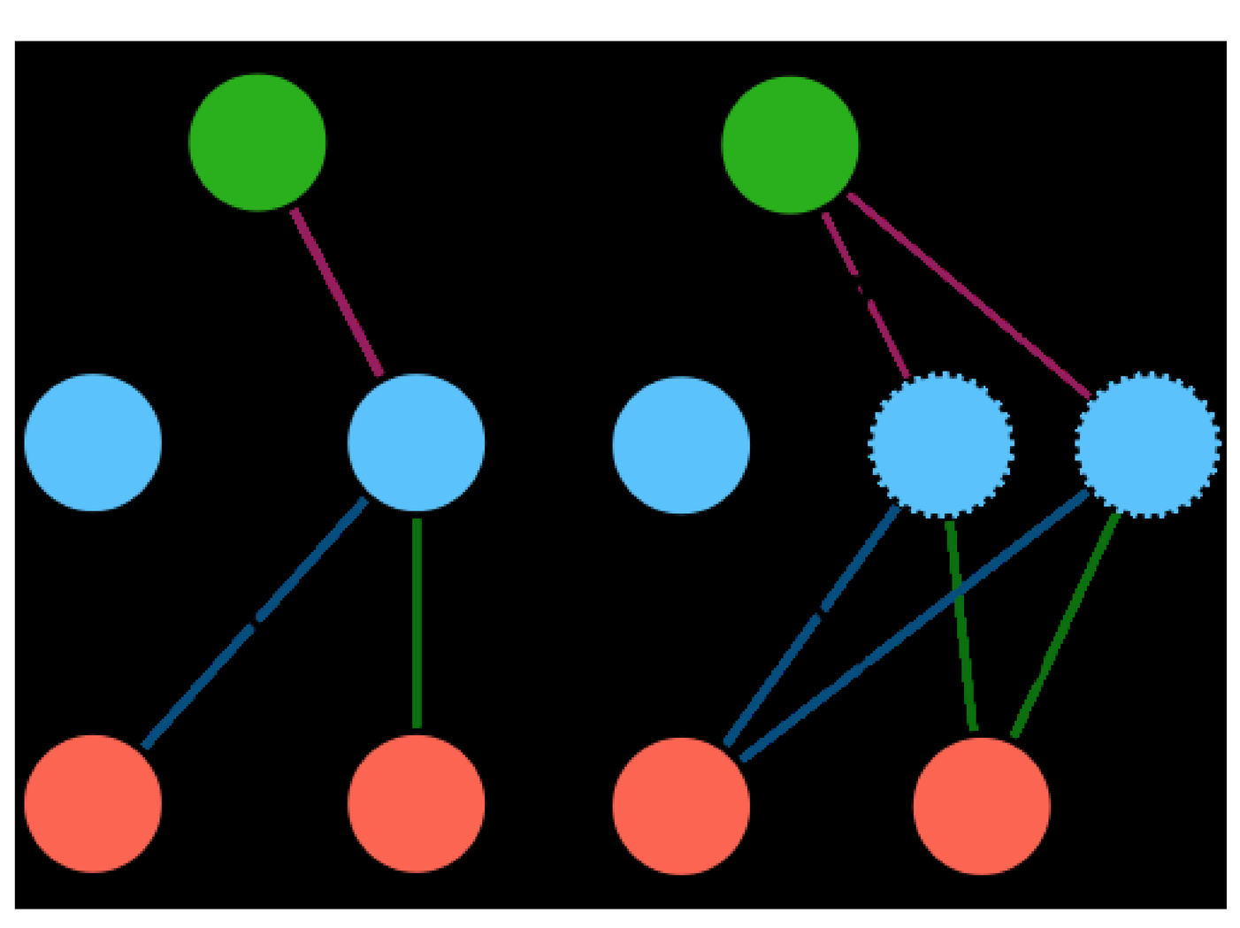
$$L(\theta) := \mathbb{E}_{x\sim D}[\Phi(\sigma(\theta; x))];$$

where $\Phi(\cdot)$ is the map from the output of the neuron to the final loss.

- Split θ into m off-springs:

$\theta \to \{\theta_i; w_i\}_{i=1}^m$, we have,

$$L(\{\theta_i; w_i\}) := \mathbb{E}_{x\sim D}\left[\Phi\left(\sum_{i=1}^m w_i \sigma(\theta_i; x)\right)\right].$$



- **Smooth loss change**:

$$\sum_{i=1}^m w_i = 1; \quad \|\theta_i - \theta\|_2 \le \epsilon; \forall i.$$

Deriving optimal splitting strategies

- Structural descent at stable local minima

$$\min_{m; \{\theta_i\}; \{w_i\}} L_m(\{\theta_i; w_i\}) - L(\theta); \; s.t. \; \|\theta_i - \theta\| \le \epsilon; \; \sum_{i=1}^m w_i = 1; w_i > 0. \quad (1)$$

- The optimum of Eqn. 1 is determined by

$$\min_{m; \{\theta_i\}; \{w_i\}} L_m(\{\theta_i; w_i\}) - L(\theta) = \frac{\epsilon^2}{2} \min\{\underbrace{\lambda_{\min}(S(\theta))}_{\text{splitting index}}; 0\} + O(\epsilon^3);$$

$$\text{with } S(\theta) = \underbrace{\mathbb{E}_{x\sim D}[\nabla_\sigma \Phi(\sigma(\theta; x)) \nabla^2_{\theta\theta} \sigma(\theta; x)]}_{\text{Splitting matrix}};$$

where $\lambda_{\min}(S(\theta))$ denotes the minimum eigenvalue of $S(\theta)$.

Optimal splitting

- When $\lambda_{\min}(S(\theta)) \ge 0$, no splitting
- When $\lambda_{\min}(S(\theta)) < 0$:

$m = 2; \; \theta_1 = \theta + \epsilon v_{\min}(S(\theta)); \; \theta_2 = \theta - \epsilon v_{\min}(S(\theta)); \; w_1 = w_2 = 1/2.$

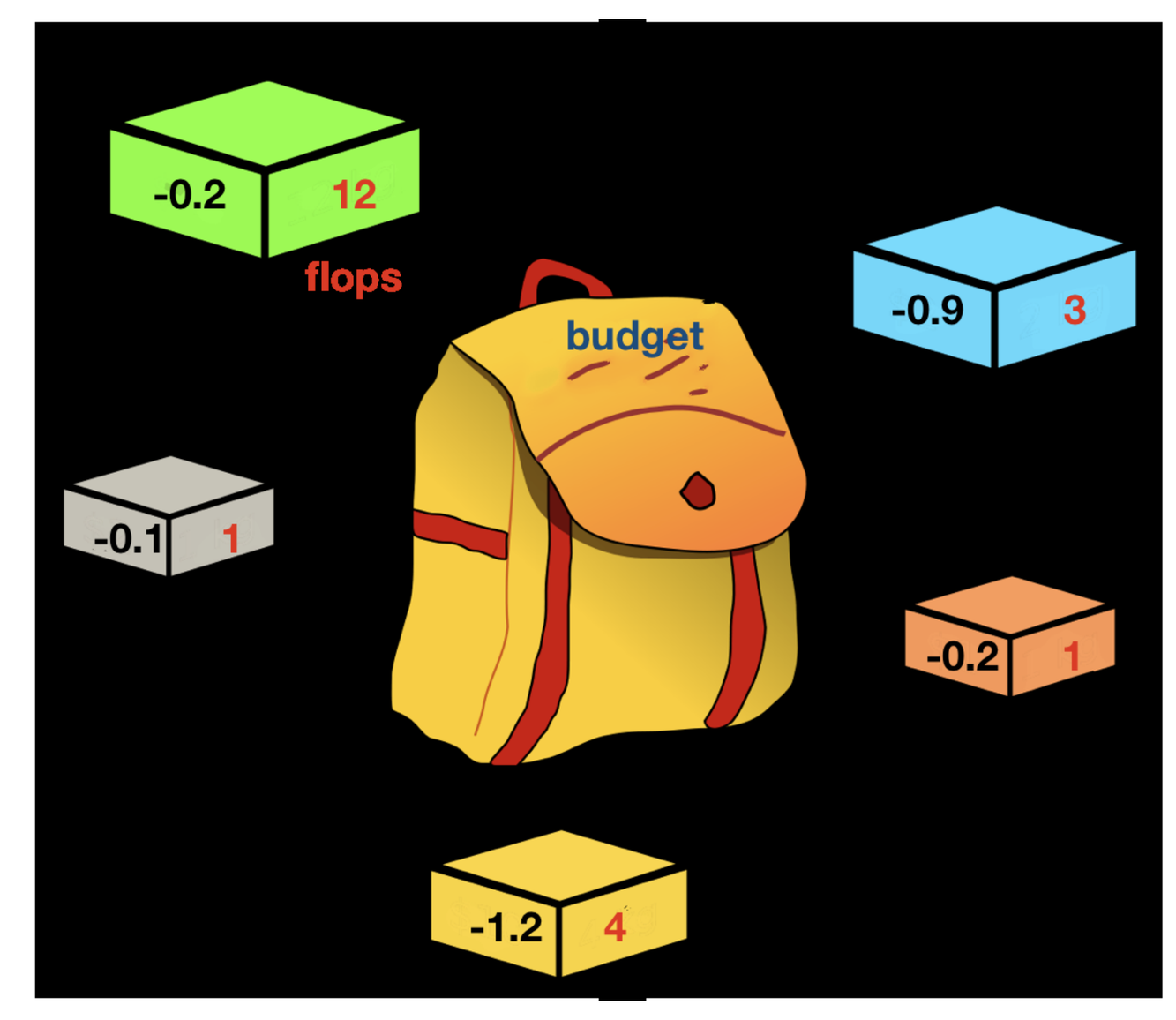
The corresponding maximum decrease of loss is $\epsilon^2 \lambda_{\min}(S(\theta))/2$.

Energy-aware splitting

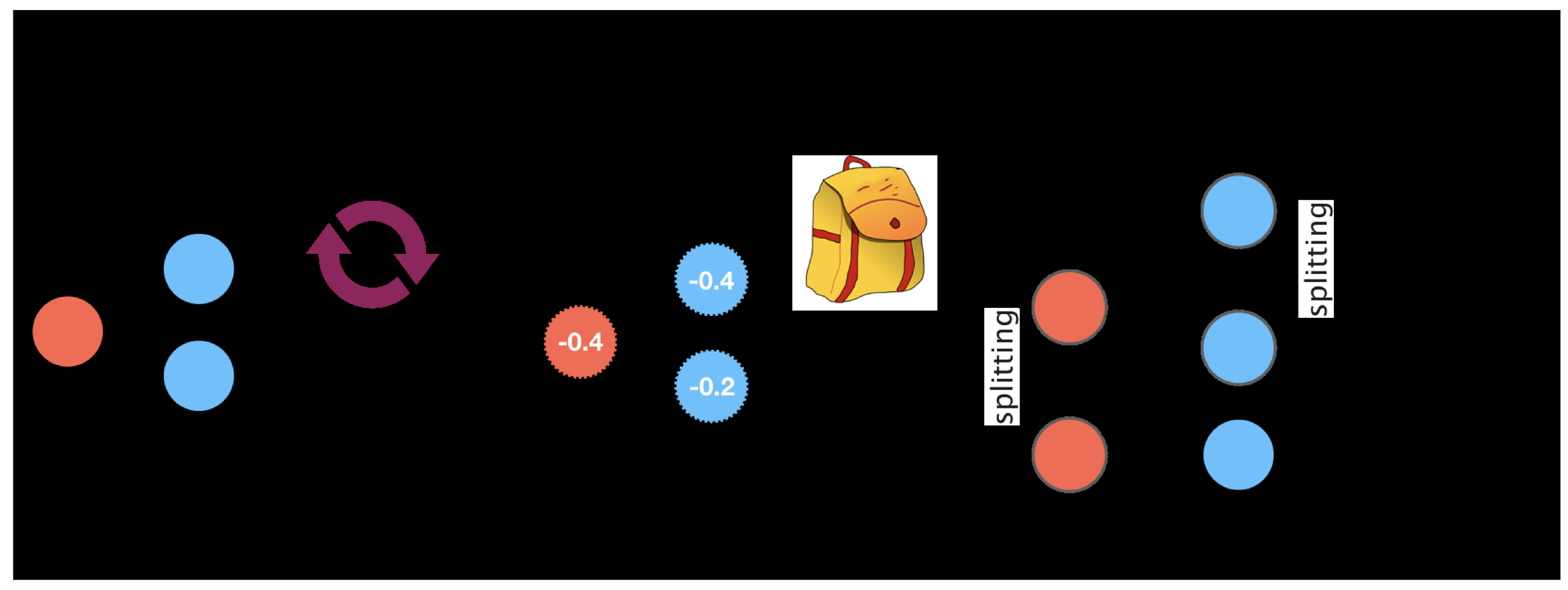
- Our formulation

$$\min \sum_{\ell=1} \underbrace{\lambda_{\min}(S(\theta_\ell))}_{gain} \delta_\ell \quad \delta_\ell \in \{0, 1\}$$

$$s.t. \sum_{\ell=1} \underbrace{e_\ell}_{ops} \delta_\ell \le \text{budget}$$



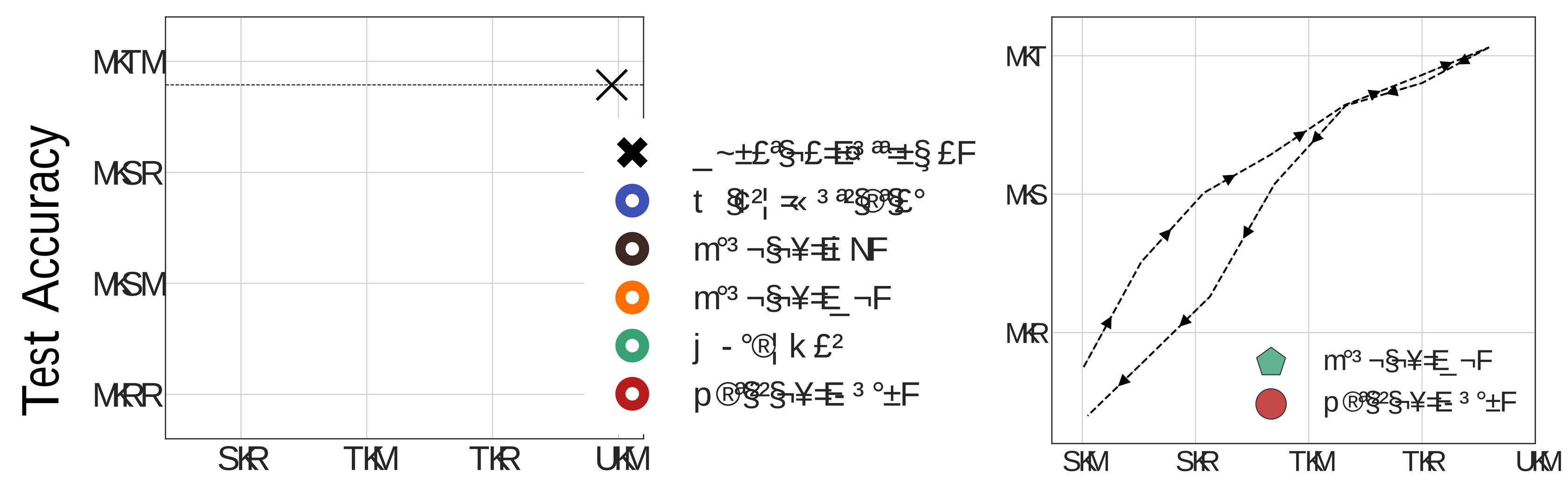
Main algorithm



Experiments

Results on CIFAR100

- We apply splitting on a small version of MobileNetV1 Howard et al., 2017



(a) Log10(flops) (b) Log10(flops)

Results on ImageNet

- MobileNetV1

Model	MACs (G)	Top-1 Accuracy	Top-5 Accuracy
MobileNetV1 (1.0x)	0.569	72.93	91.14
Splitting-4	**0.561**	**73.96**	**91.49**
MobileNetV1 (0.75x)	0.317	70.25	89.49
AMC He el al., 2018	0.301	70.50	89.30
Splitting-3	**0.292**	**71.47**	**89.67**
MobileNetV1 (0.5x)	0.150	65.20	86.34
Splitting-2	**0.140**	**68.26**	**87.93**
Splitting-1	0.082	64.06	85.30
Splitting-0 (seed)	0.059	59.20	81.82

- MobileNetV2

Model	MACs (G)	Top-1 Accuracy	Top-5 Accuracy
MobileNetV2 (1.0x)	0.300	72.04	90.57
Splitting-3	**0.298**	**72.84**	**90.83**
MobileNetV2 (0.75x)	0.209	69.80	89.60
AMC He el al., 2018	0.210	70.85	89.91
Splitting-2	**0.208**	**71.76**	**90.07**
MobileNetV2 (0.5x)	0.097	65.40	86.40
Splitting-1	**0.095**	**66.53**	**87.00**
Splitting-0 (seed)	0.039	55.61	79.55

Conclusion

- Incremental training with splitting gradient.
- Simple and fast, promising in practice.
- Opens a new dimension for energy-efficient NAS.